Listing of the Claims

- 1. (Original) A method of adaptive sampling of a structure in a data set, the method comprising the steps of: identifying a region of the structure comprising high frequency signals; performing a first sampling with a first sampling rate, resulting in a sampled structure comprising first sample points; wherein the first sampling is performed along a trajectory intersecting the region comprising the high frequency signals, wherein the region of the structure comprising high frequency.
- 2. (Original) The method according to claim 1, wherein the region of the structure comprising high frequency signals is identified by performing a second sampling with a second sampling rate; wherein the first sample rate is higher than the second sampling rate.
- 3. (Original) The method according to claim 1, wherein the sampled structure is rendered on the basis of the first sampling; and wherein an average pixel value of a pixel in the region comprising the high frequency signals is determined by evaluating an average of the values of the first sample points.
- 4. (Original) The method according to claim 1, wherein the structure is determined by an iso-surface rendering procedure.
- 5. (Original) The method according to claim 1, wherein the trajectory along which the first sampling is performed is a line intersecting the region comprising the high frequency signals.
- 6. (Original) The method according to claim 1, wherein the region of the structure comprising the high frequency signals is an edge.
- 7. (Original) The method according to claim 1, wherein the adaptive sampling includes a ray casting; and wherein the ray casting is used for detecting the edge.

- 8. (Original) The method according to claim 1, wherein the structure comprises a surface; wherein the surface comprises a surface variation; and wherein the trajectory extends along a direction of a maximum surface variation.
- 9. (Original) The method according to claim 1, wherein the method is used for virtual endoscopy.
- 10. (Original) An image processing device for adaptive sampling of a structure in a data set, the image processing device comprising: a memory for storing the data set; an image processor adapted for performing the following operation: loading the data set; identifying a region of the structure comprising high frequency signals; performing a first sampling with a first sampling rate, resulting in a sampled structure comprising first sample points; wherein the first sampling is performed along a trajectory intersecting the region comprising the high frequency signals.
- 11. (Original) A scanner system, comprising: a memory for storing a data set; an image processor adapted for performing adaptive sampling of a structure in the data set, wherein the image processor is adapted for performing the following operation: loading the data set; identifying a region of the structure comprising high frequency signals; performing a first sampling with a first sampling rate, resulting in a sampled structure comprising first sample points; wherein the first sampling is performed along a trajectory intersecting the region comprising the high frequency signals.
- 12. (Original) A scanner system according to claim 11, wherein the scanner system is one of a CT scanner system and a MR scanner system.
- 13. (Currently Amended) A computer program product stored on a computer readable medium, wherein the computer program is for performing adaptive sampling of a structure in a data set, wherein the computer program product causes—an image processor to perform performs the following operation when the computer program is executed on the image processor: loading the data set; identifying a region of the structure comprising high frequency signals; performing a first sampling with a first sampling rate, resulting in a sampled structure comprising first sample points; wherein

the first sampling is performed along a trajectory intersecting the region comprising the high frequency signals.